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Challenges and opportunities in reliability engineering: the big KID (Knowledge, Information and Data)



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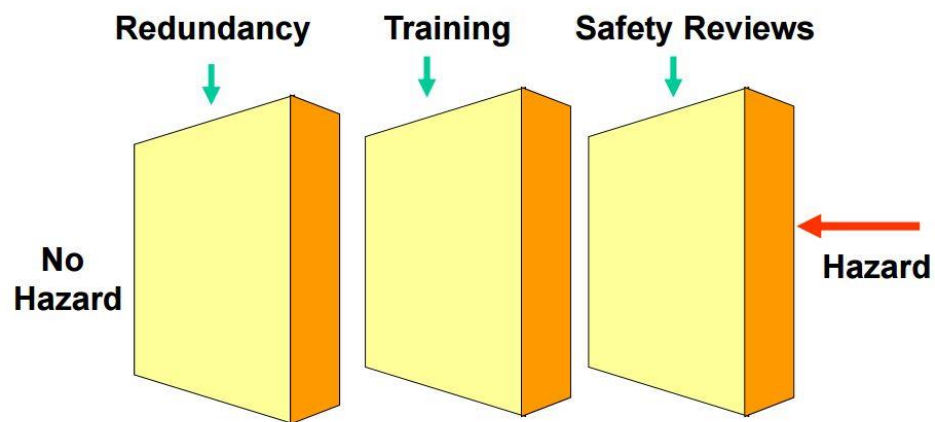
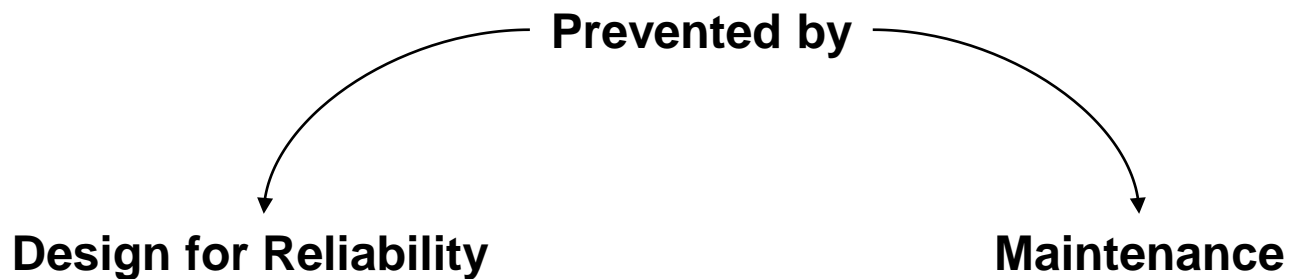
Aramis Srl, Italy





Problem statement

Failures





INDUSTRY



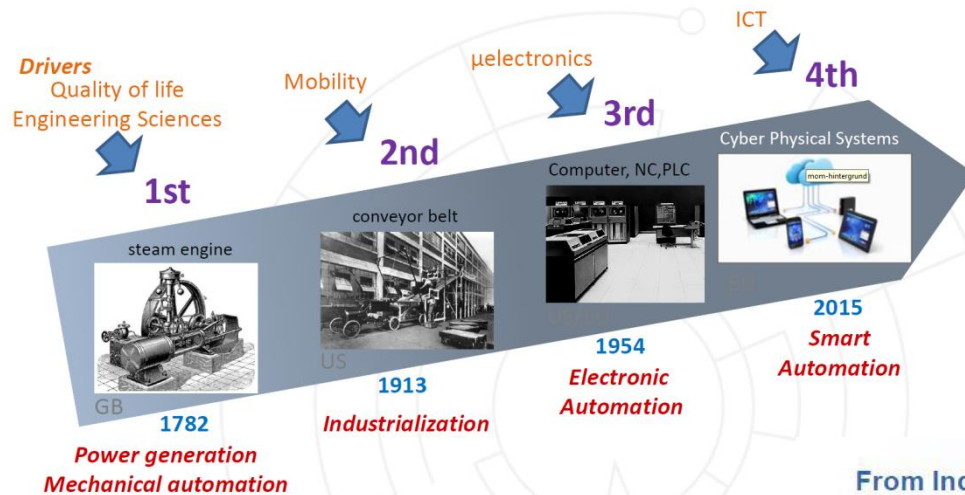


Industry 1-2-3-4

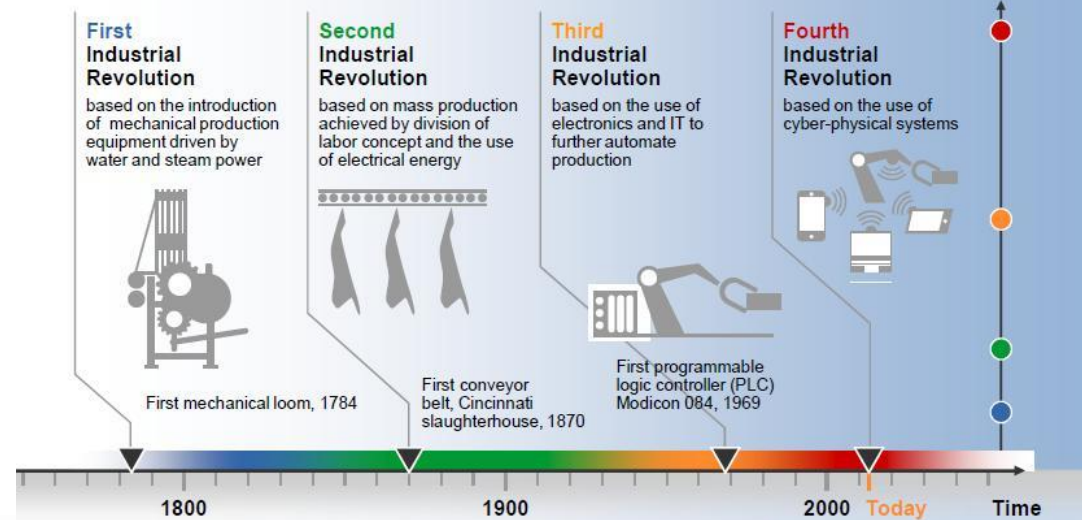


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The 4th Industrial Revolution - „Industry 4.0“



From Industry 1.0 to Industry 4.0



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(SMART) Reliability Engineering





The Big KID

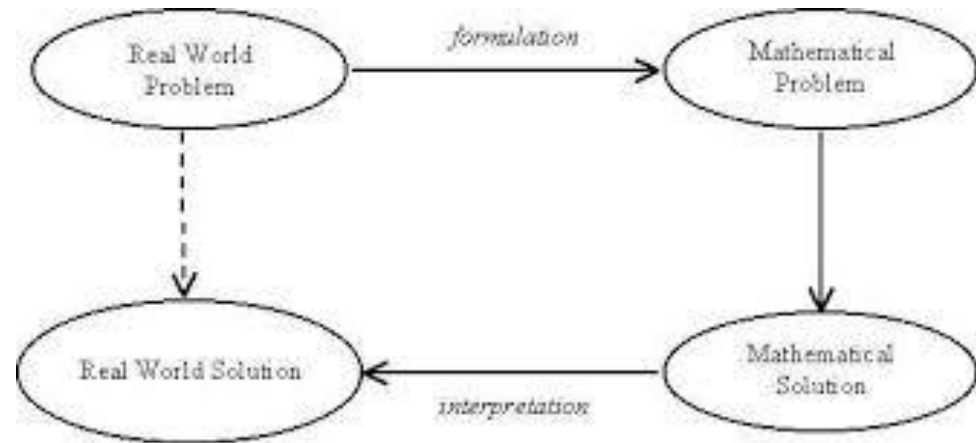




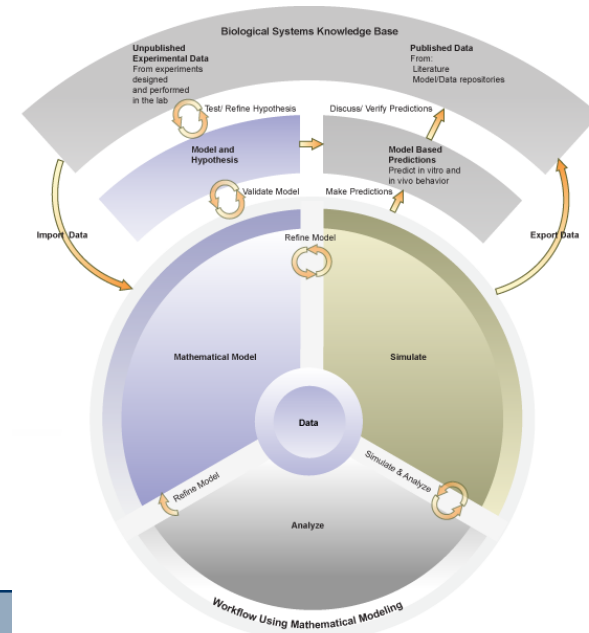
Big Knowledge(ID)



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$$\begin{aligned}
 v_q &= -r_s i_q + \frac{\omega_r}{\omega_b} \Psi_d + \frac{p}{\omega_b} \Psi_q, \\
 v_d &= -r_s i_d - \frac{\omega_r}{\omega_b} \Psi_q + \frac{p}{\omega_b} \Psi_d, \\
 v_o &= -r_s i_o + \frac{p}{\omega_b} \Psi_o, \\
 0 &= r_{aq} i_{aq} + \frac{p}{\omega_b} \Psi_{aq}, \\
 v_f &= r_f i_f + \frac{p}{\omega_b} \Psi_f, \\
 0 &= r_{ad} i_{ad} + \frac{p}{\omega_b} \Psi_{ad}, \\
 T_e &= \frac{3}{2} \frac{P}{2} \frac{1}{\omega_b} (\Psi_d i_q - \Psi_q i_d), \\
 p\omega_r &= \frac{P}{2J} (T_a - T_e),
 \end{aligned}
 \quad
 \begin{aligned}
 p\theta_r &= \omega_r, \\
 p\theta_e &= \omega_e, \\
 \delta &= \theta_r - \theta_e, \\
 \omega_m &= \frac{2}{p} \omega_r,
 \end{aligned}
 \quad (1)$$



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Big (K)Information(D)



Global
21st Business
Education Learning
Literacy Advantage
Transparency Prosperity
Information
Competitive
Workforce Stability
Third Security
Access
Health
Wave
Century
Lifelong
Beacons
Cultural
ICTs
Personal
Economic
Responsibility
Society
Competence
Empowerment
Unserved
National
Competencies
Underserved

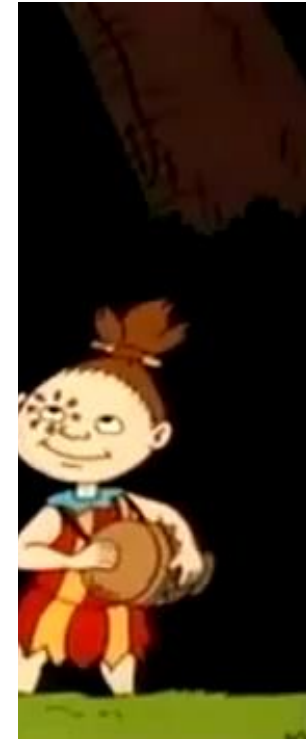
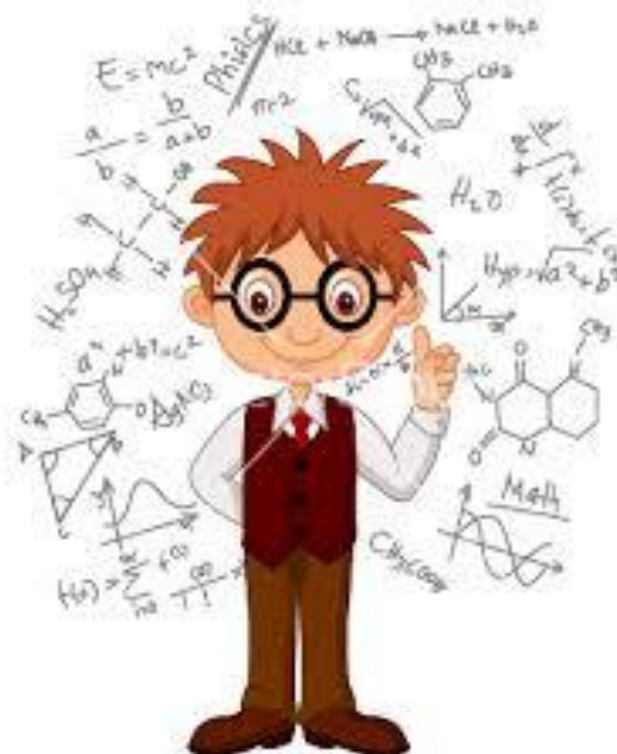




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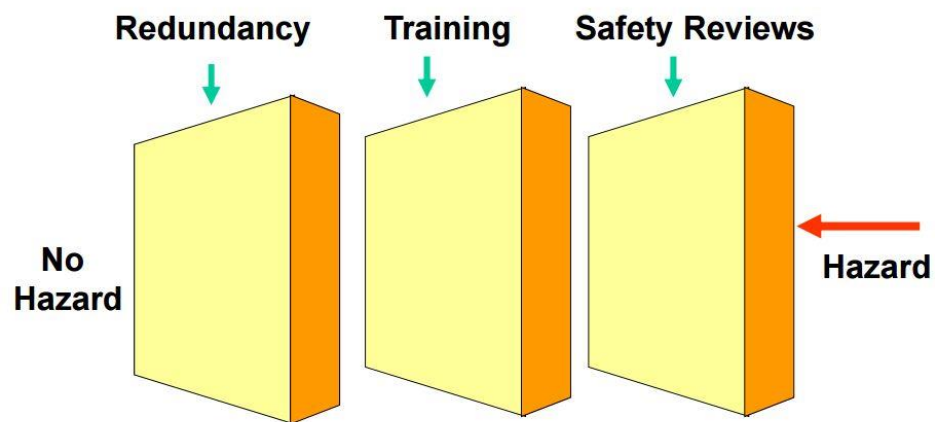
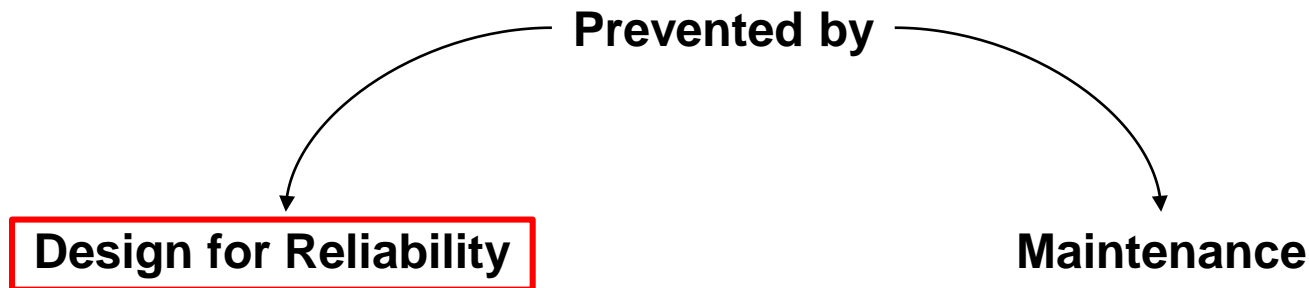
Can the Big KID become SMART for Reliability Engineering ?





Problem statement

Failures





Reliability analysis for Design for Reliability:

From failure modeling to degradation-to-failure modeling





Reliability analysis for Design for Reliability:

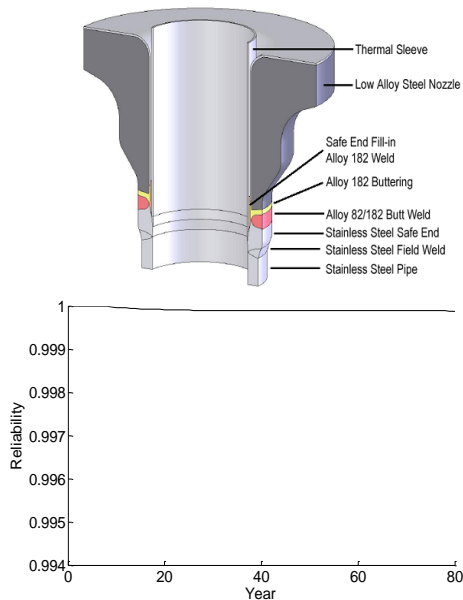
From failure modeling to degradation-to-failure modeling

Integrating physics-of-failure knowledge in reliability models

- **Multi-State Physic-Based Models**



Reliability ?



Highly reliable

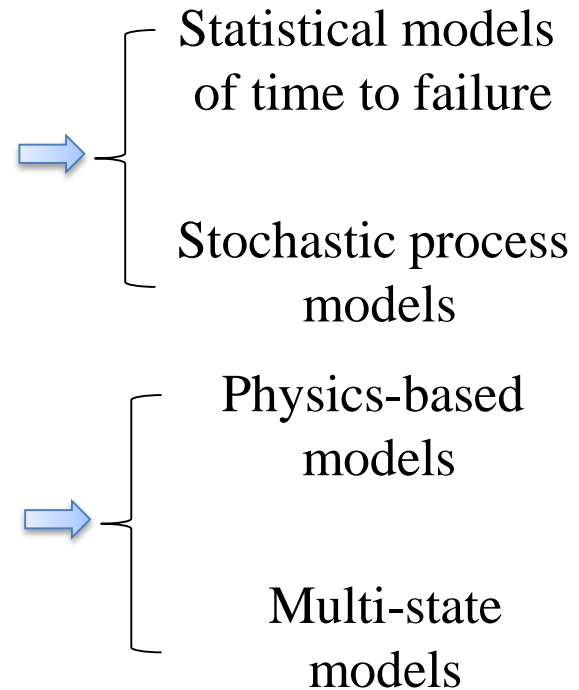
KID
(Knowledge, Information, Data)



Sufficient failure
data

Physics knowledge
Expert judgment
Field data

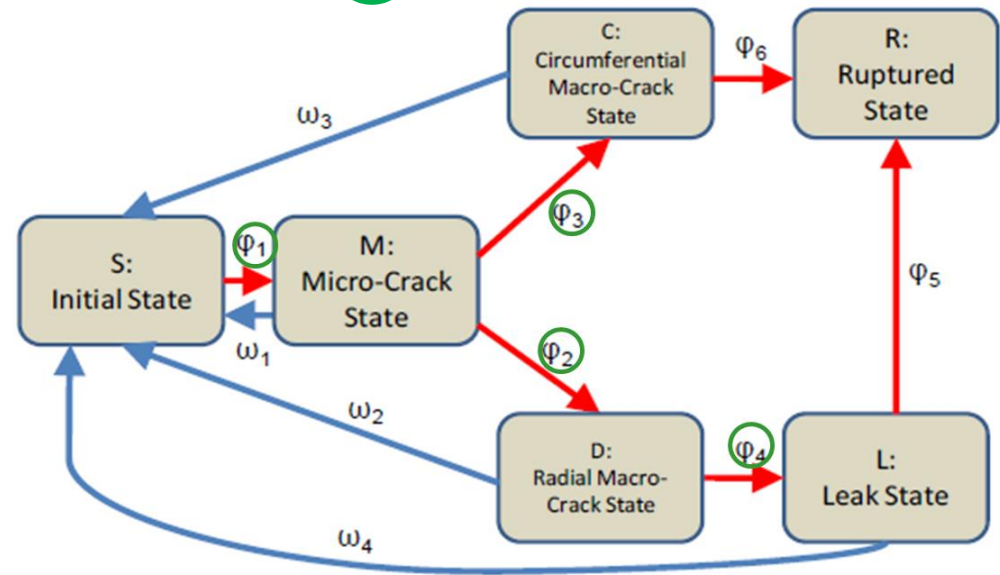
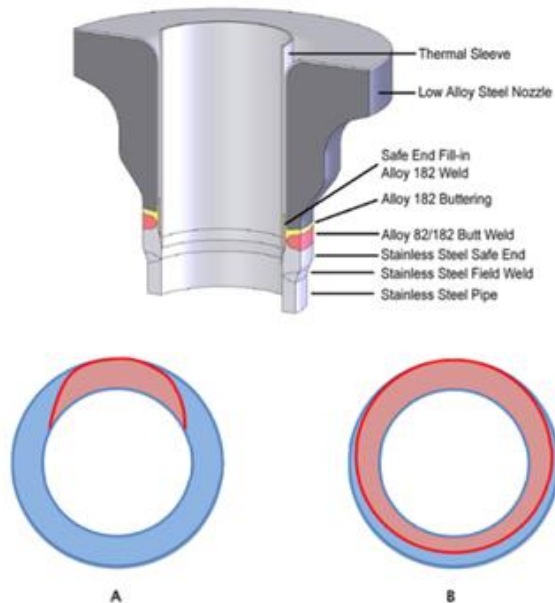
Model





Alloy 82/182 dissimilar metal weld of piping in a PWR primary coolant system

Physical laws



Multi-state physics model of crack development in Alloy 82/182 dissimilar metal weld

$$\varphi_1 = \int \left(\frac{b}{\tau} \right) \cdot \left(\frac{t}{\tau} \right)^{b-1} \cdot f_{PDF}(\tau, b) d\tau db$$

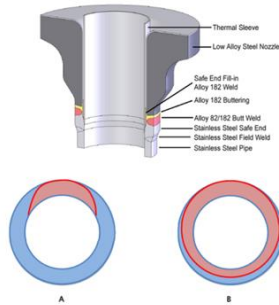
$$\varphi_2 = \begin{cases} \frac{a_D P_D}{\dot{a}_M u^2 (1 - P_D (1 - a_D / (u \dot{a}_M)))}, & \text{if } u > a_D / \dot{a}_M \\ 0, & \text{else} \end{cases}$$

$$\varphi_3 = \begin{cases} \frac{a_C P_C}{\dot{a}_M u^2 (1 - P_C (1 - a_C / (u \dot{a}_M)))}, & \text{if } u > a_C / \dot{a}_M \\ 0, & \text{else} \end{cases}$$

$$\varphi_4 = \begin{cases} \frac{1}{w}, & \text{if } w > (a_L - a_D) / \dot{a}_M \\ 0, & \text{else} \end{cases}$$

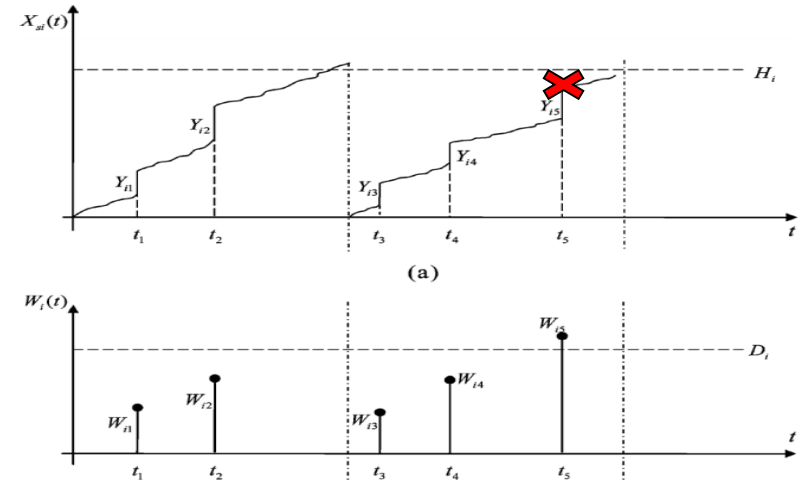


Random shocks



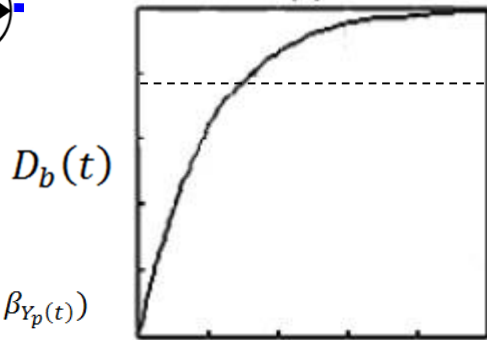
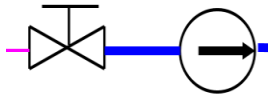
Degradation process

Random shock process



Dependences in degradation processes

Internal leak

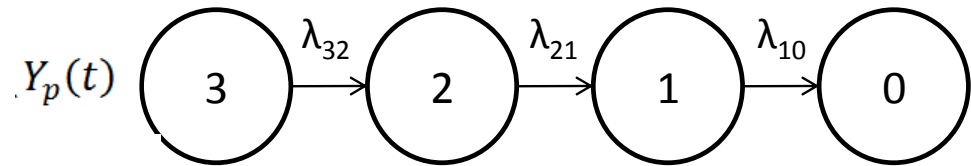


$$\dot{D}_b(t) = \omega_b(1 + \beta_{Y_p(t)})$$

$$\mathbf{Z}(t) = \begin{pmatrix} D_b(t) \\ Y_p(t) \end{pmatrix}$$

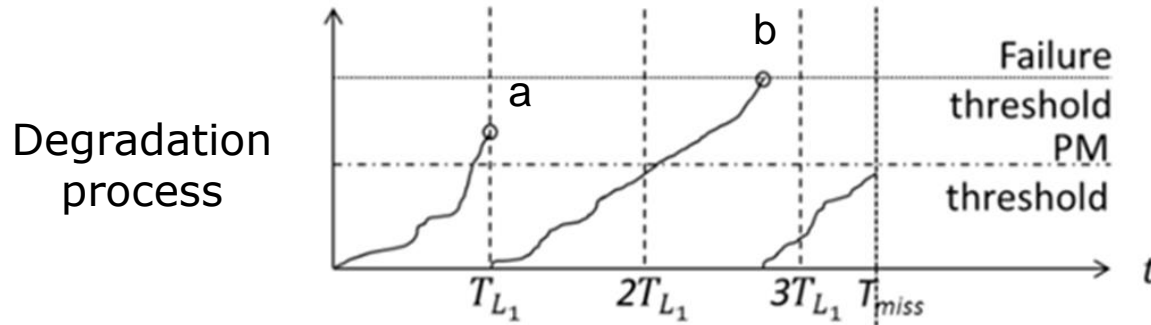
Initial state

Failure state





Maintenance

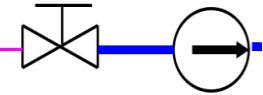


Preventive maintenance (a)

Corrective maintenance (b)

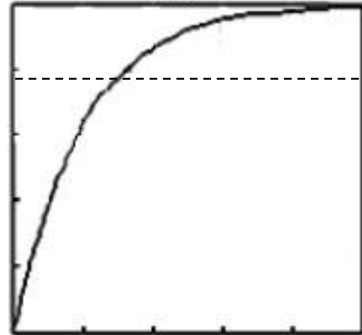


Uncertainty



Internal leak

$D_b(t)$



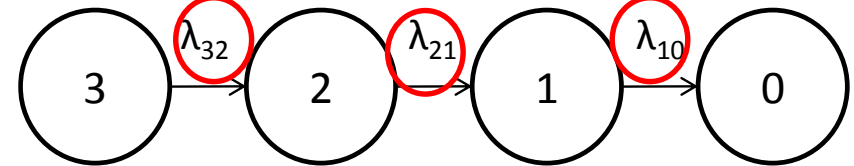
$$\dot{D}_b(t) = \omega_b (1 + \beta_{Y_p(t)})$$

○ Uncertain parameters in degradation models

Initial state

Failure state

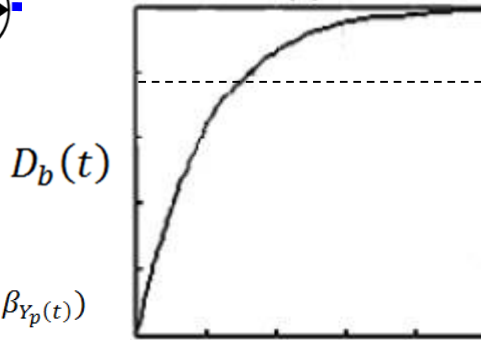
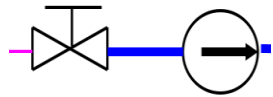
$Y_p(t)$





Degradation processes

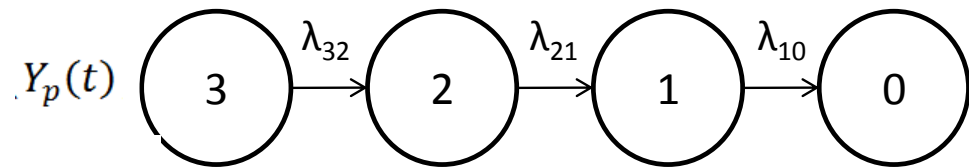
Internal leak



$$\dot{D}_b(t) = \omega_b(1 + \beta_{Y_p(t)})$$

$$\mathbf{Z}(t) = \begin{pmatrix} D_b(t) \\ Y_p(t) \end{pmatrix}$$

Initial state



Failure state

Piecewise-deterministic Markov process (PDMP)

$$\begin{aligned} \mathbf{X}(t) \quad \dot{\mathbf{X}}(t) &= \begin{pmatrix} \dot{X}_{L_1}(t) \\ \vdots \\ \dot{X}_{L_M}(t) \end{pmatrix} = \begin{pmatrix} f_{L_1}^{Y(t)}(\mathbf{X}(t), t \mid \boldsymbol{\theta}_{L_1}) \\ \vdots \\ f_{L_M}^{Y(t)}(\mathbf{X}(t), t \mid \boldsymbol{\theta}_{L_M}) \end{pmatrix} \\ &= f_L^{Y(t)}(\mathbf{X}(t), t \mid \boldsymbol{\theta}_L) \end{aligned}$$

$$\begin{aligned} \mathbf{Y}(t) \quad \lim_{\Delta t \rightarrow 0} P(\mathbf{Y}(t + \Delta t) = j \mid \mathbf{X}(t), \mathbf{Y}(t) = i, \boldsymbol{\theta}_K) / \Delta t \\ = \lambda_i(j \mid \mathbf{X}(t), \boldsymbol{\theta}_K), \forall t \geq 0, i, j \in \mathcal{S}, i \neq j \end{aligned}$$





MC Simulation

Finite-volume scheme

While $k < N_{max}$

Initialize the system by setting $Z' = \begin{pmatrix} X(0) \\ Y(0) \end{pmatrix}$ (initial state), and the time $T = 0$ (initial system time)

Set $t' = 0$ (state holding time)

While $T < T_{mix}$

Sample a t' by using the probability density function (3.7)

Sample an arrival state Y' for stochastic process $Y(t)$ from all the possible states by using the conditional probability distribution (3.8)

Set $T = T + t'$

Calculate $X(T)$ by using the physics eq. (3.3)

Set $Z' = \begin{pmatrix} X(T) \\ Y' \end{pmatrix}$

If $T \leq T_{mix}$

If $Z' \in \mathcal{F}$

Set $k' = k' + 1$

Break

End if

Else (when $T > T_{mix}$)

Calculate $Z(T_{mix})$

If $Z(T_{mix}) \in \mathcal{F}$

Set $k' = k' + 1$

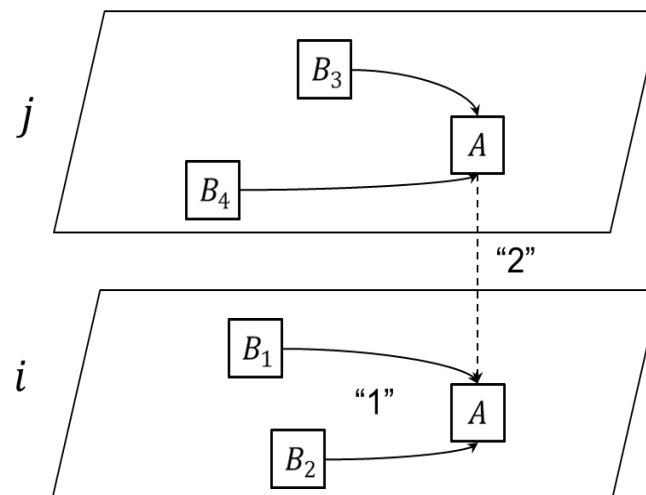
Break

End if

End if

End While

$$P_{n+1}(A, i | \theta) = \frac{1}{1 + \Delta t b_A^i} \widehat{P}_{n+1}(A, i | \theta) + \Delta t \sum_{j \in S} \frac{a_A^{ji}}{1 + \Delta t b_A^j} \widehat{P}_{n+1}(A, j | \theta)$$





Reliability analysis for Design for Reliability:

From failure modeling to degradation-to-failure modeling

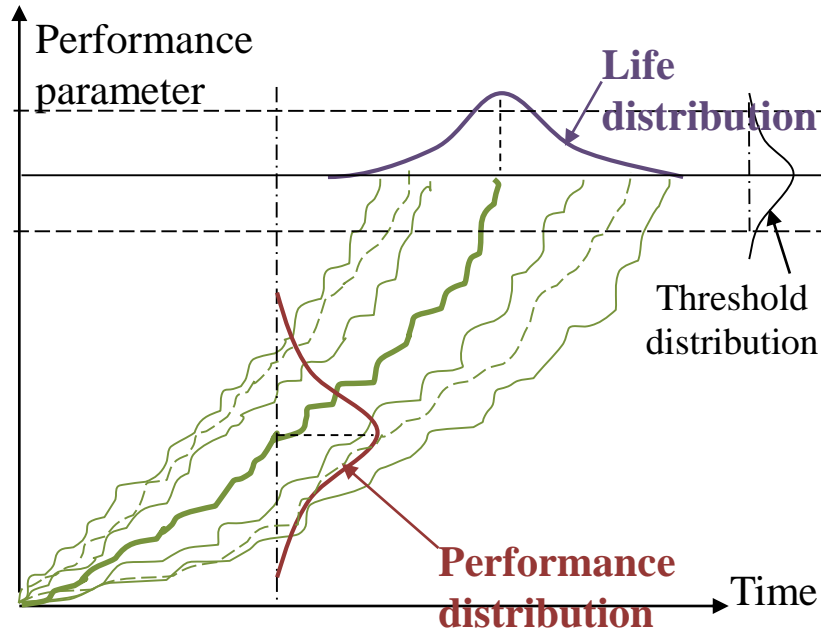
Integrating physics-of-failure knowledge in reliability models

- Multi-State Physic-Based Models

?And the data?



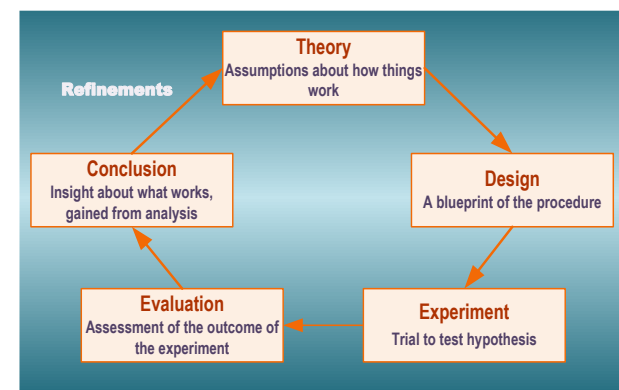
ADT Procedure



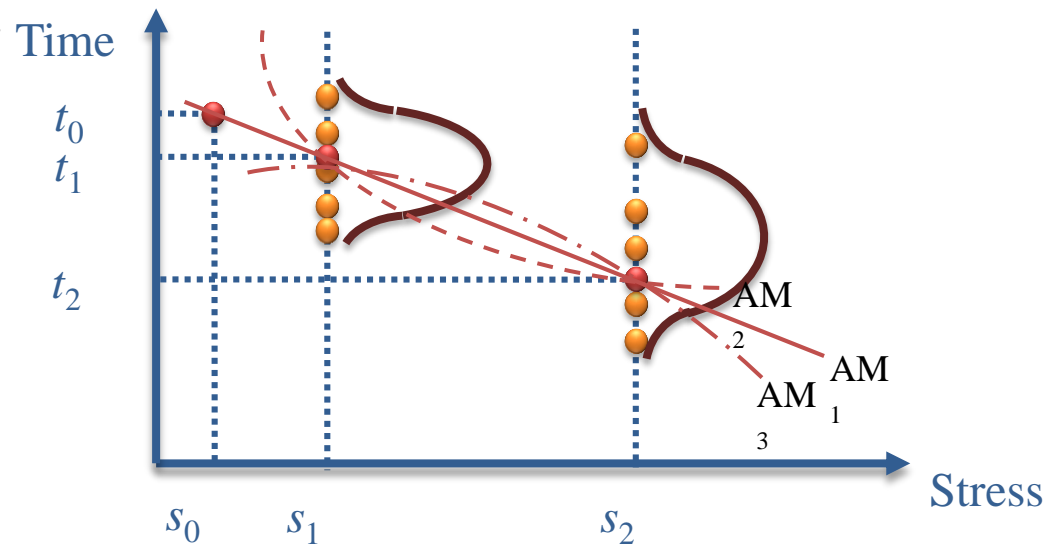
Degradation Model:
Degradation VS Time

Stochastic process or degradation-path:

Wiener process: $Y(t) = \sigma B(t) + d(S)t$



General testing procedure



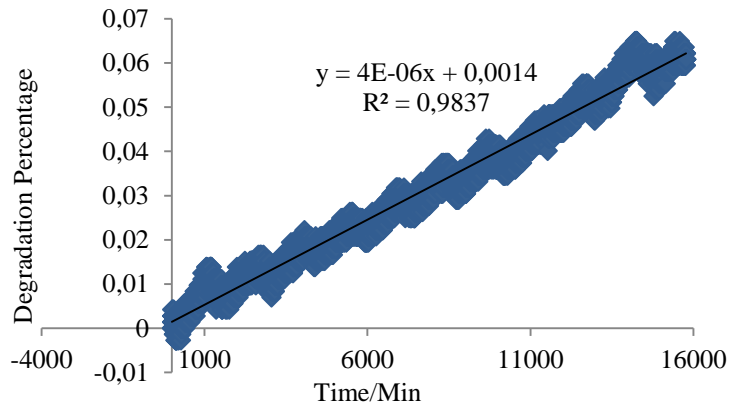
Acceleration Model:
Stress VS Time

Physical or empirical models:

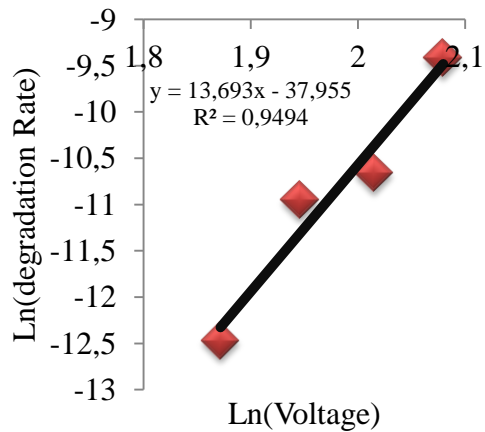
Arrhenius: $d(S) = Ae^{-E_a/kS}$

Data Analysis

Trend analysis & Accelerability Verification:



Degradation VS Time



Time VS Stress

Degradation
Process Model

Maximum
Likelihood

Degradation
Fitting

Parameter
Estimation

$$Y_i(t) = \sigma B(t) + d(S_i) \cdot t + y_0, d(S_i) = \exp[a + b\varphi(S_i)]$$

$$L(\sigma, a, b) \propto \prod_{l=1}^k \prod_{i=1}^{n_l} \prod_{j=1}^{m_l-1} \frac{1}{\sqrt{2\pi\sigma^2\Delta t_{ij}}} \exp\left\{-\frac{[x_{ij} - d(S_i) \cdot \Delta t_{ij}]^2}{2\sigma^2\Delta t_{ij}}\right\}$$

$$\sum_{l=1}^k \sum_{i=1}^{n_l} \sum_{j=1}^{m_l-1} \{x_{ij} - \exp[a + b \cdot \varphi(S_i)] \cdot \Delta t\} = 0$$

$$E[Y_i(t)] = d(S_i) \cdot t + y_0 \xrightarrow{\text{LSE}} d(S_i)$$

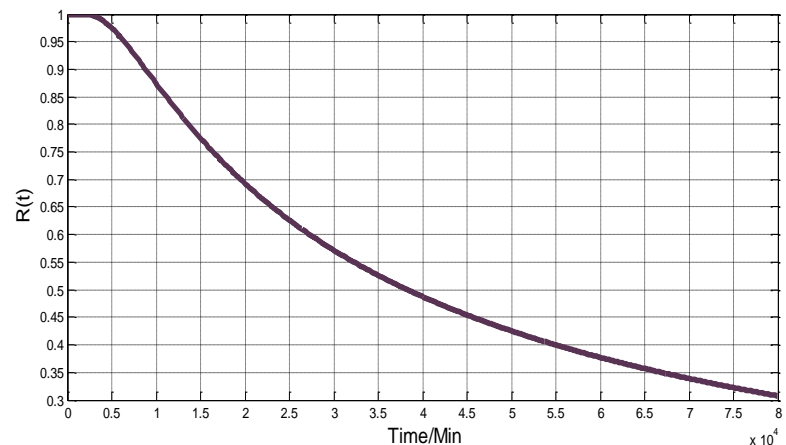
$$d(S_i) = \exp[a + b\varphi(S_i)] \xrightarrow{\text{LSE}} \hat{a} + \hat{b}$$

$$\hat{\sigma}^2 = \frac{1}{n \cdot (m-k)\Delta t} \cdot \sum_{l=1}^k \sum_{i=1}^{n_l} \sum_{j=1}^{m_l-1} [x_{ij} - \exp[\hat{a} + \hat{b} \cdot \varphi(S_i)] \Delta t]^2$$

Parameter estimation:

\hat{a}	\hat{b}	$\hat{\sigma}^2$
- 36.961	13.112	8.278e-07

Reliability Prediction:



Challenges in ADT

Degradation trend

- The whole trend is defined (linear, exponential, etc.)

Aleatory uncertainty

- Inherent randomness
- Probability

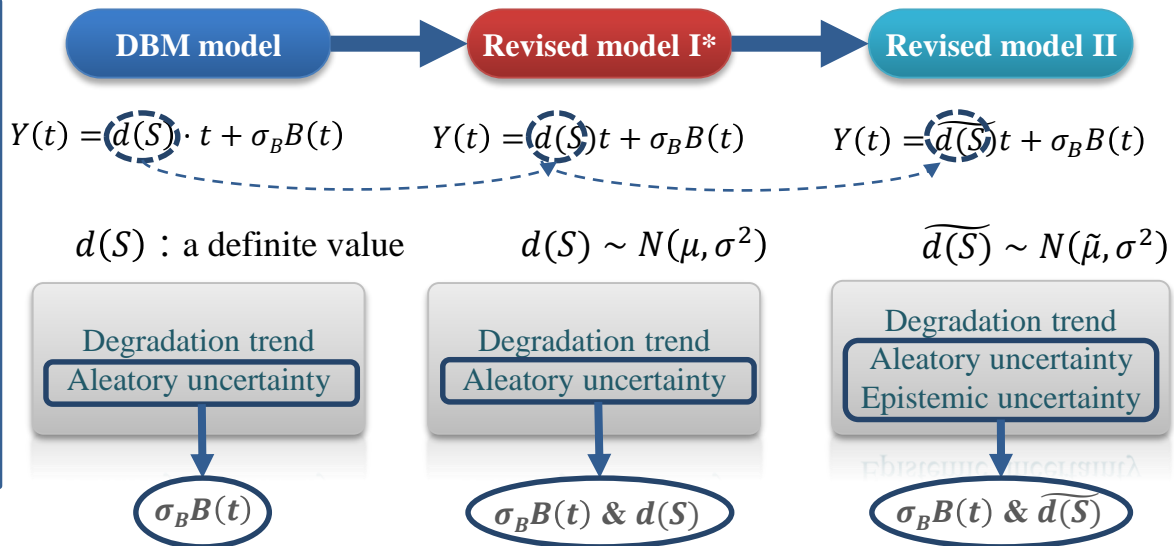
Epistemic uncertainty

- Incomplete knowledge due to limited information
- Interval, possibility, etc.

Challenges:

- ✓ Traditional methods mainly model degradation trend and aleatory uncertainty.
- ✓ Failing to consider epistemic uncertainty may cause serious reliability evaluation problems.

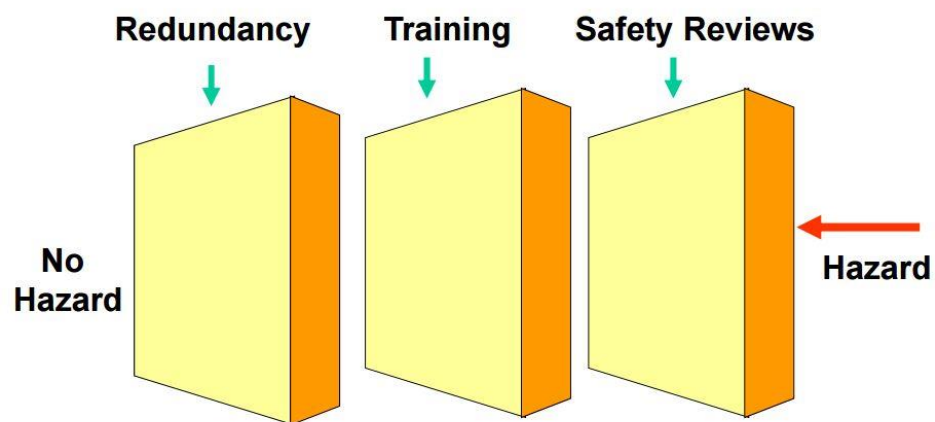
Stochastic Process – some revised models:





Problem statement

Failures





Maintenance:

Integrating physics knowledge and data:

- Prognostics and Health Management (PHM)



Maintenance

1950

Corrective
Maintenance

1980

Planned Periodic
Maintenance

2000

Condition Based
Maintenance (CBM)

2016

Predictive
Maintenance (PrM)



Prognostics and Health Management (PHM)

PHM is fostered by advancements in:



Sensor

Algorithm

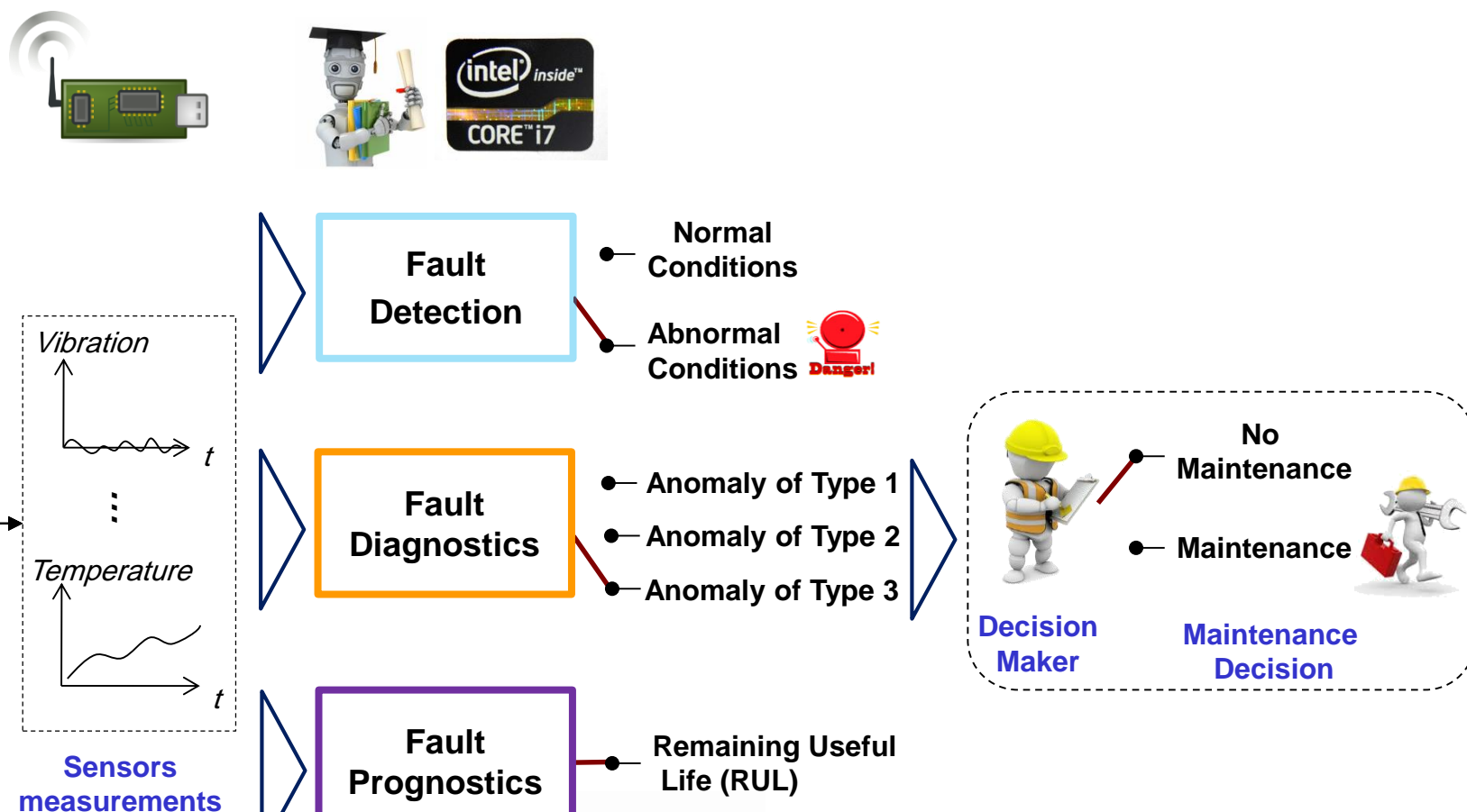
Computation power





PHM for what?

PHM in support to CBM and PrM





- **Increase** maintainability, availability, safety, operating performance and productivity
- **Reduce** downtime, number and severity of failure and life-time cost



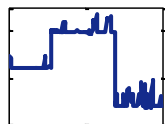
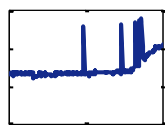
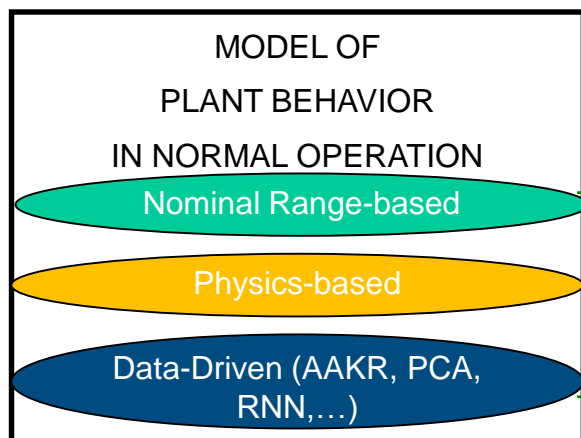
PHM: how? (Fault detection)



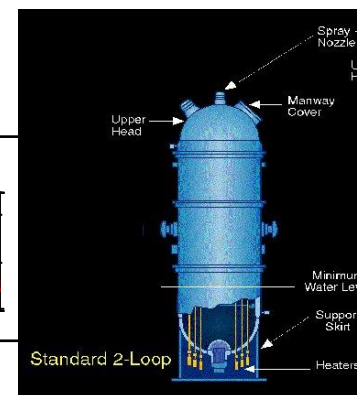
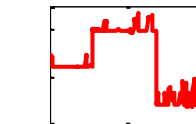
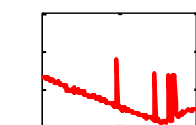
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Signal
reconstructions

Real
measurements



\neq

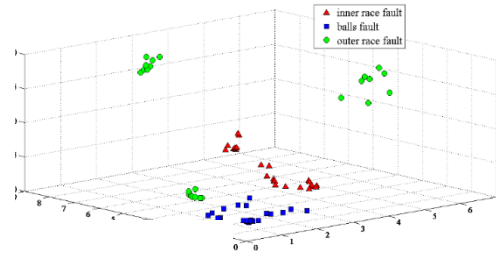


Abnormal Condition





- Signal measurements representative of the fault classes: « x_1, x_2, \dots, x_n , class»



x_1
 x_2
 x_3

**Empirical
Classifier**

- C_1 = Inner race
- C_2 = Balls
- C_3 = Outer race

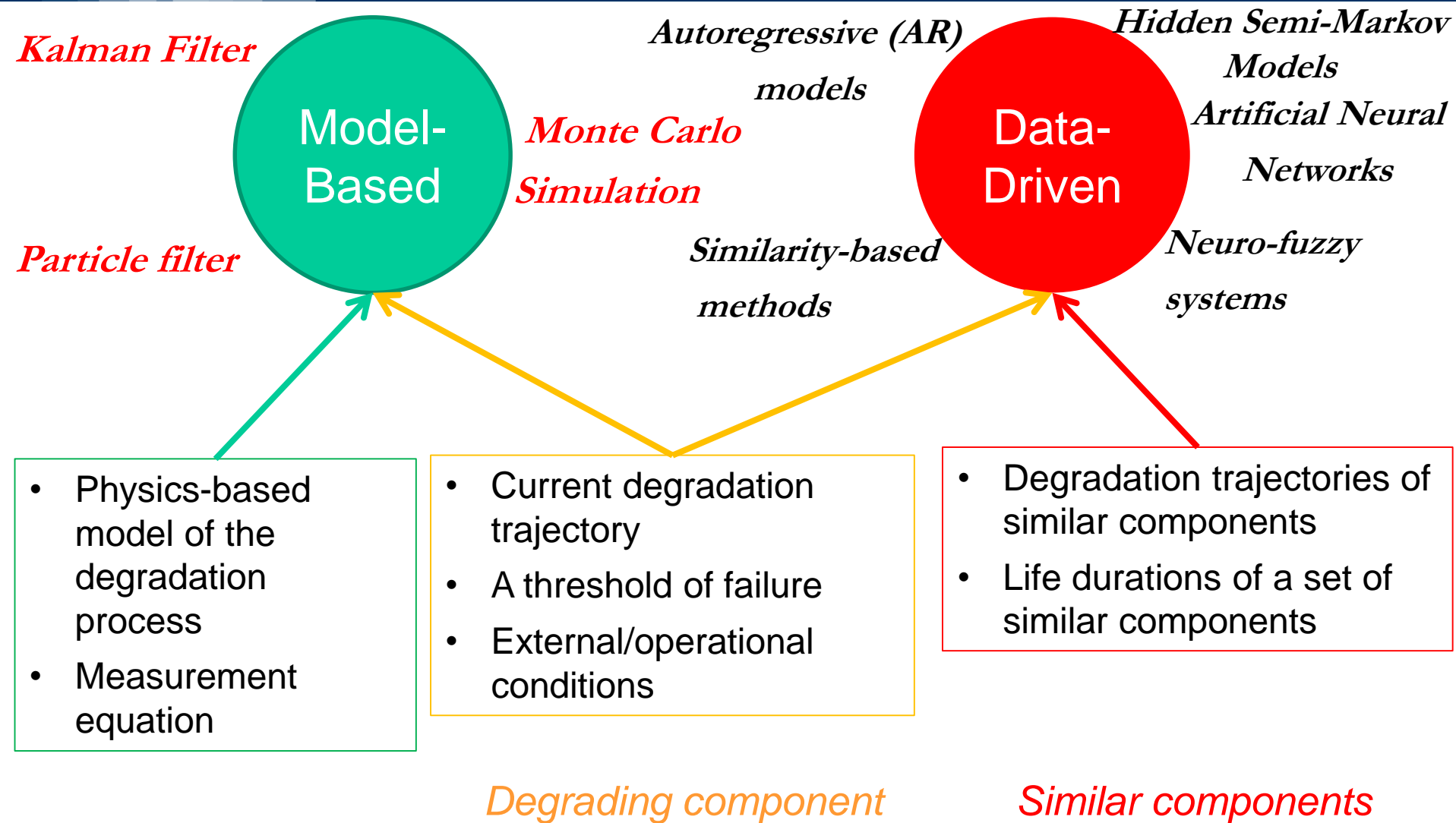
- Empirical classification methods:
 - **Support Vector Machines**
 - **K-Nearest Neighbours**
 - **Multilayer Perceptron Neural Networks**
 - **Supervised clustering algorithms**
 - **Ensemble of classifiers**



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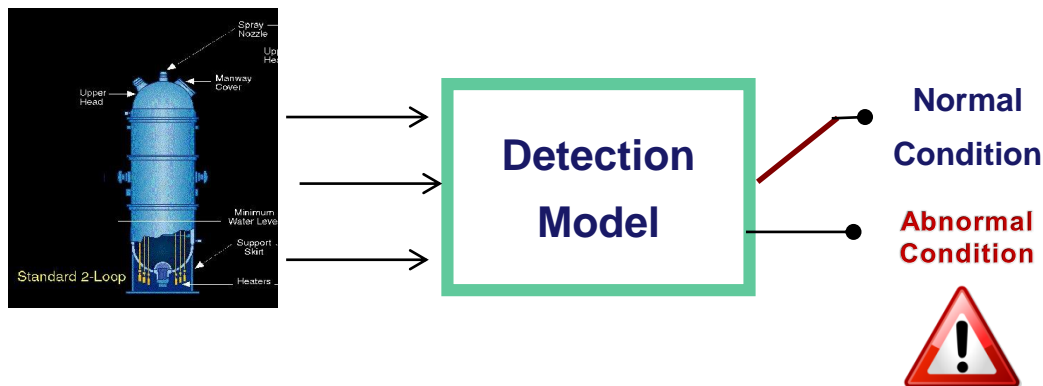
- Accuracy





- Accuracy
 - Fault Detection:
 - ❑ Low rate of False Alarms
 - ❑ Low rate of Missing Alarms

Example:

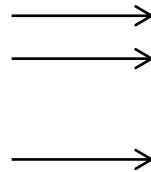
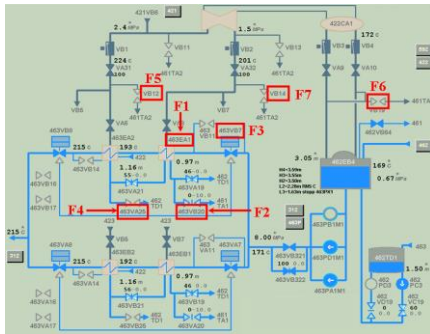


False Alarm Rates	Missing Alarm Rates
0.54%	0.98%



PHM: performance ? (diagnostics)

- Accuracy
 - Fault diagnostics:
 - ❑ Low Misclassification rate

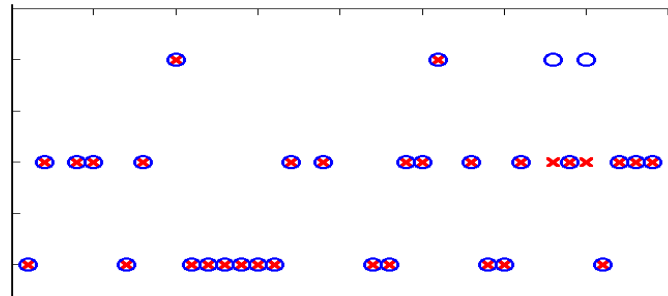


Diagnostic
Model

C_1

C_2

C_3



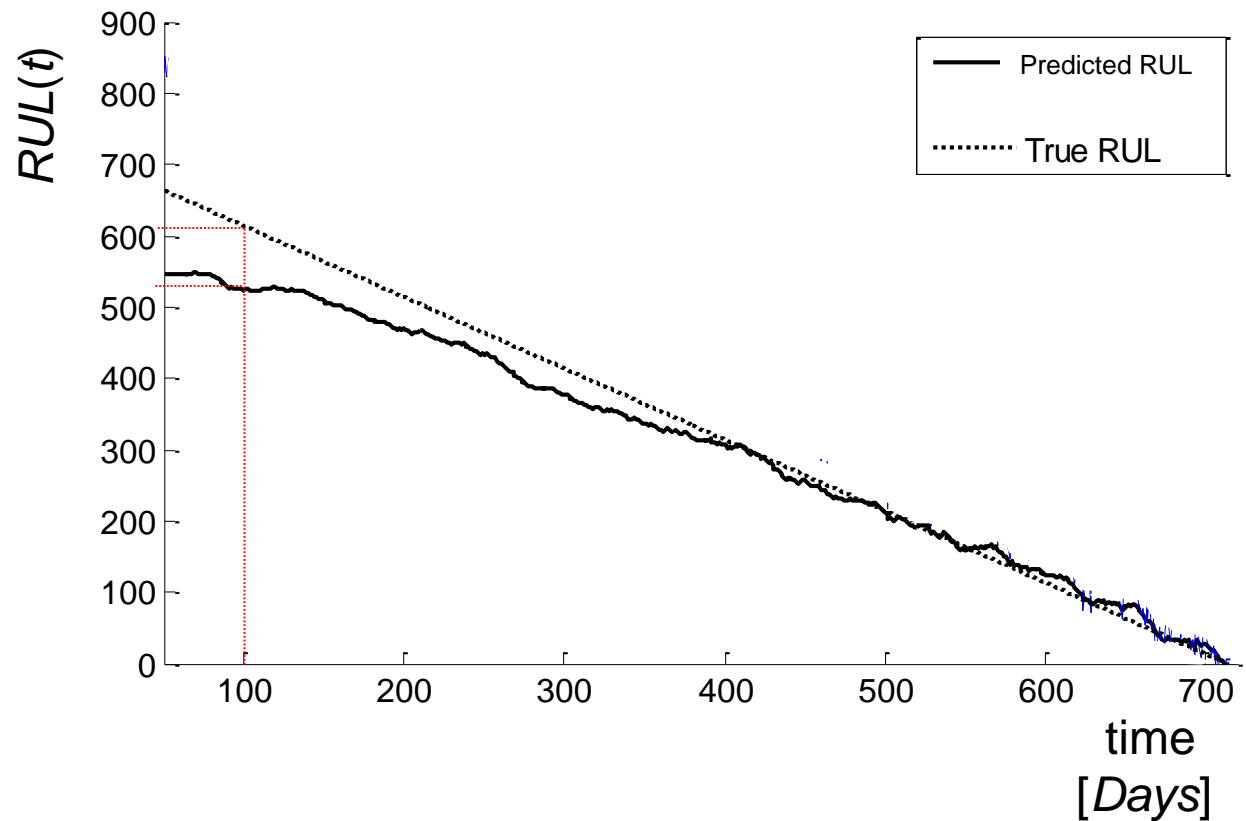
o = true

x = diagnostic model

Misclassification rate = 2.58%



- Accuracy
 - Prognostics



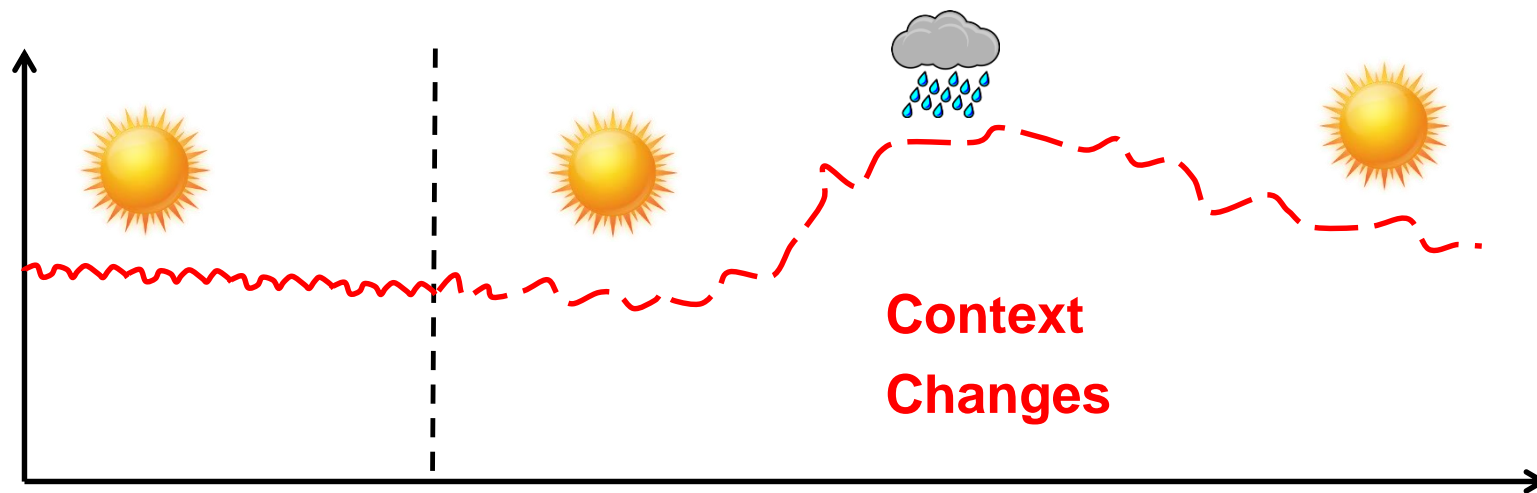


PHM &

- 1) Context changing
- 2) Uncertainty management
- 3) Fleet
- 4) Return of Investment
- 5) Safety



Context changing: concept

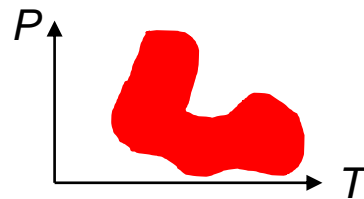




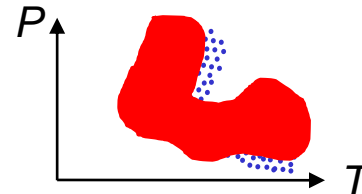
Monitoring components of a (e.g. nuclear power) plant

The detection model should be able to follow the process changes:

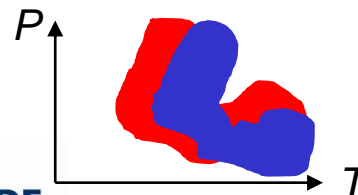
- Incremental learning of the new data that gradually becomes available
- No necessity of human intervention for:
 - selecting recent normal operation data
 - building the new model



New data are coming

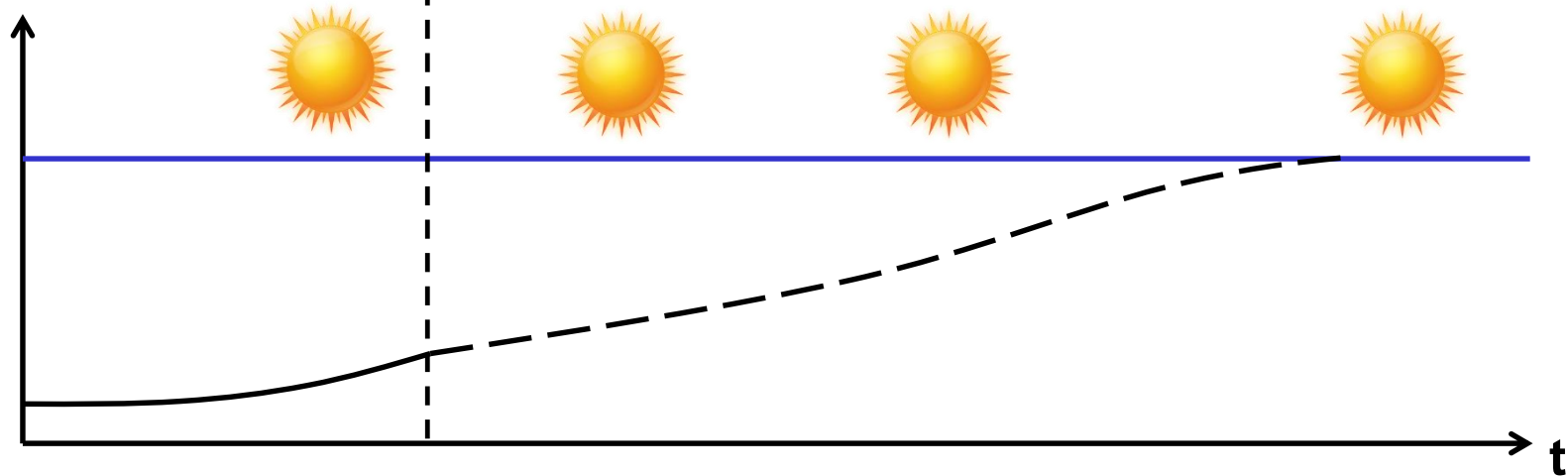


Automatic updating of the model



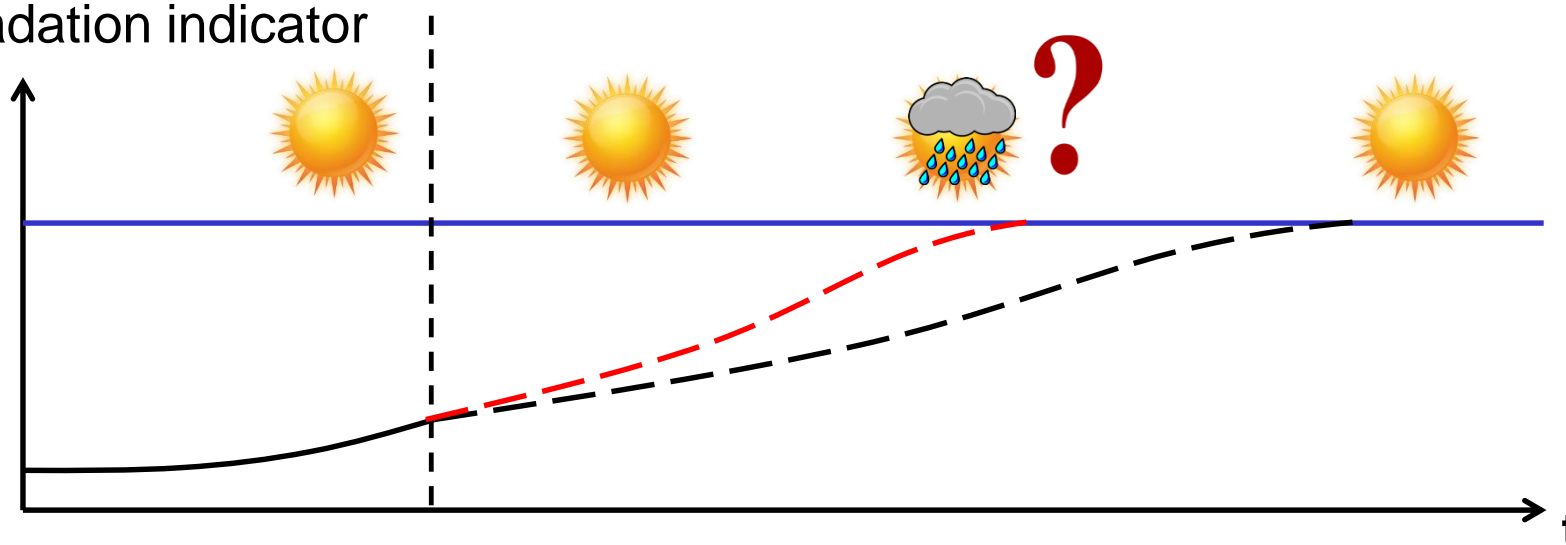


Degradation indicator



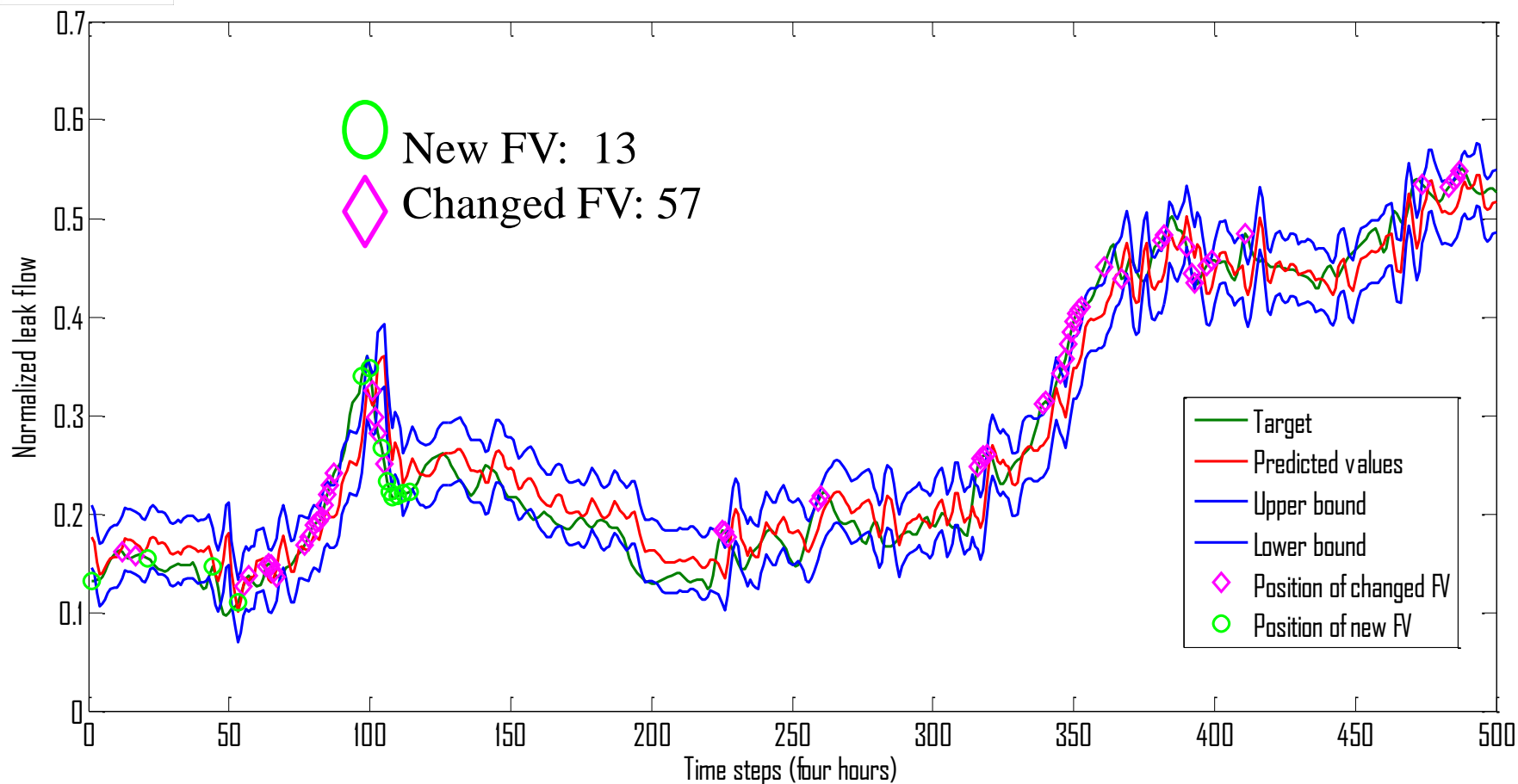


Degradation indicator





Context changing (fault prognostics)





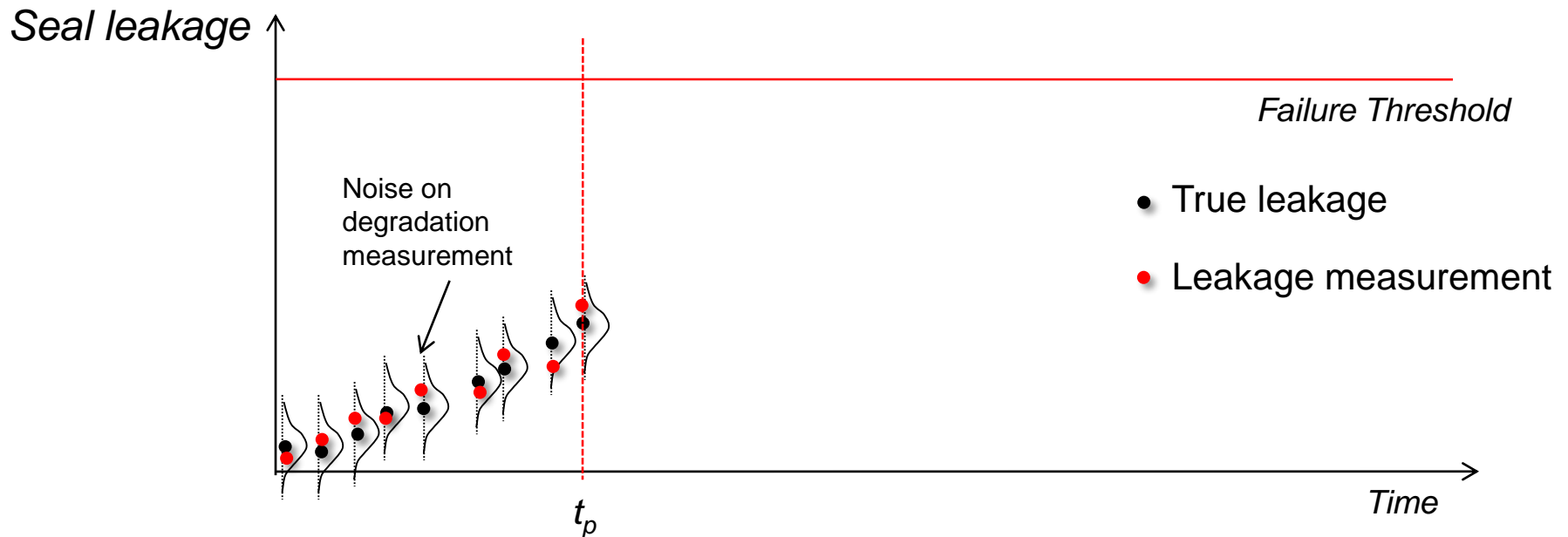
PHM &

- 1) Context Changing
- 2) Uncertainty management
- 3) Fleet
- 4) Return Of Investment
- 5) Safety



Sources of uncertainty:

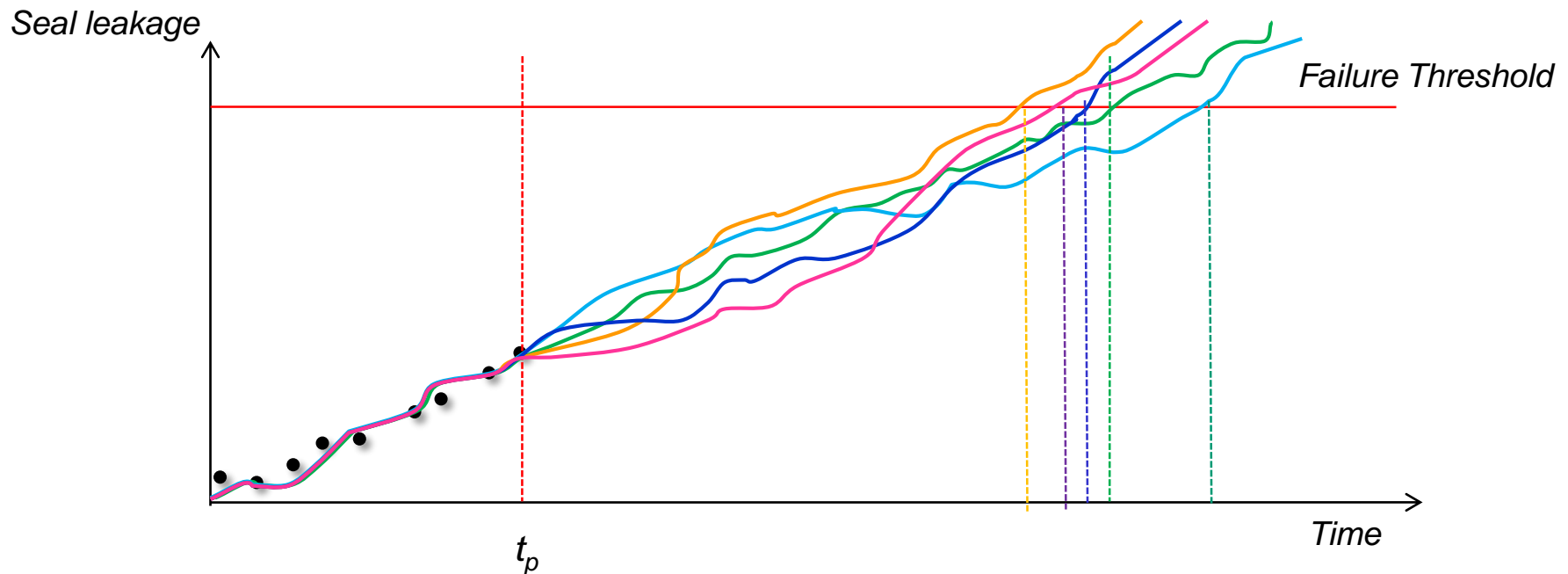
1) noise on the observations (measurements)





Sources of uncertainty:

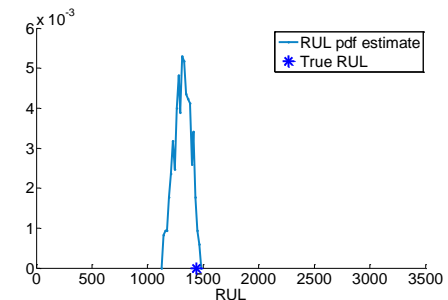
- 1) noise on the observations (measurements)
- 2) intrinsic stochasticity of the degradation process





Sources of uncertainty:

- 1) noise on the observations (measurements)
- 2) intrinsic stochasticity of the degradation process
- 3) unknown future external/operational conditions
- 4) Modeling errors, i.e. inaccuracy of the prognostic model used to perform the prediction



Uncertainty on the RUL prediction ?



Maximum acceptable failure probability is 5%

Prognostic Model

Probability to have a failure in this interval is lower than 5%

Present Time

time for maintenance

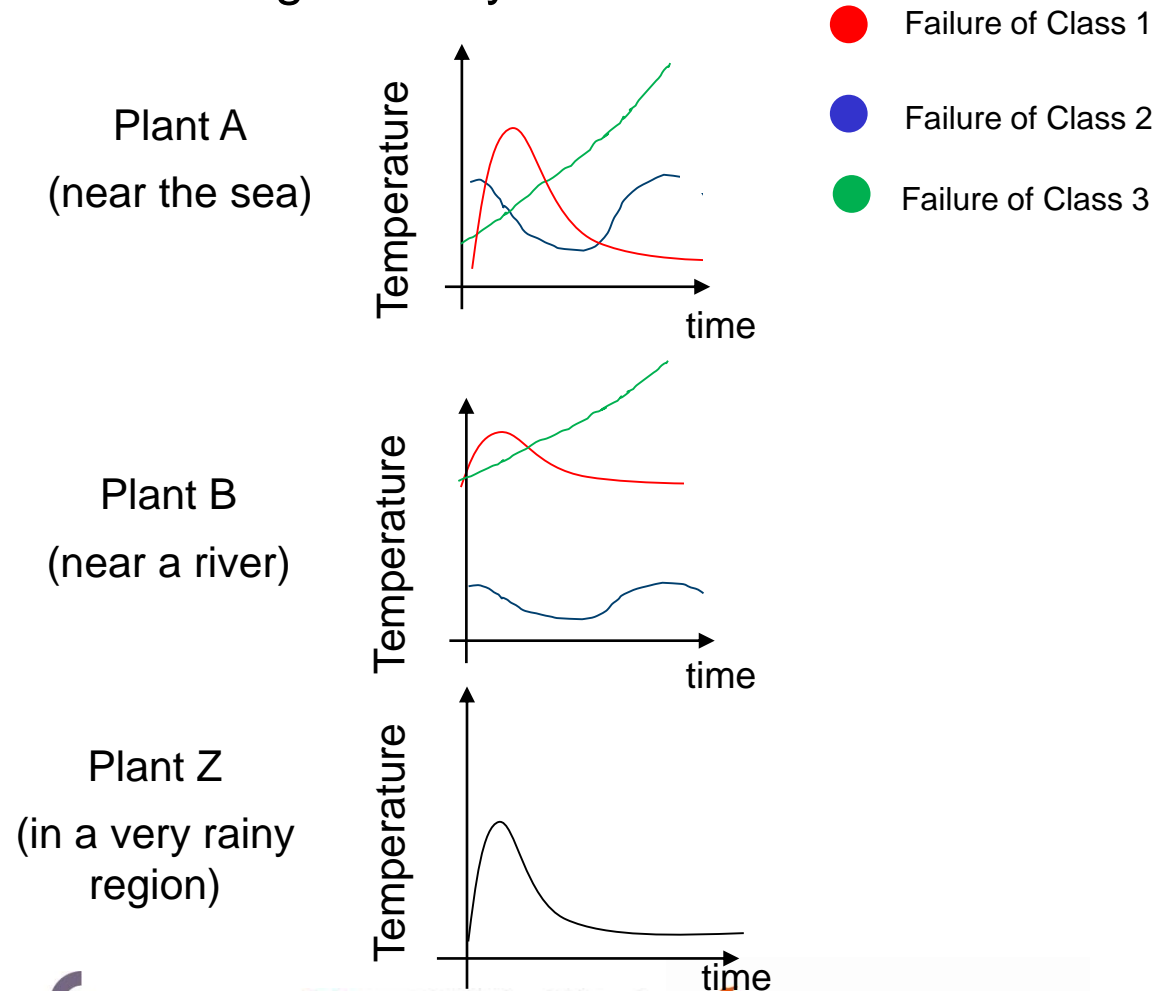


PHM &

- 1) Context Changing
- 2) Uncertainty management
- 3) Fleet
- 4) Return of Investment
- 5) Safety



- Can we use data from similar industrial plants of the same fleet to build diagnostic systems?





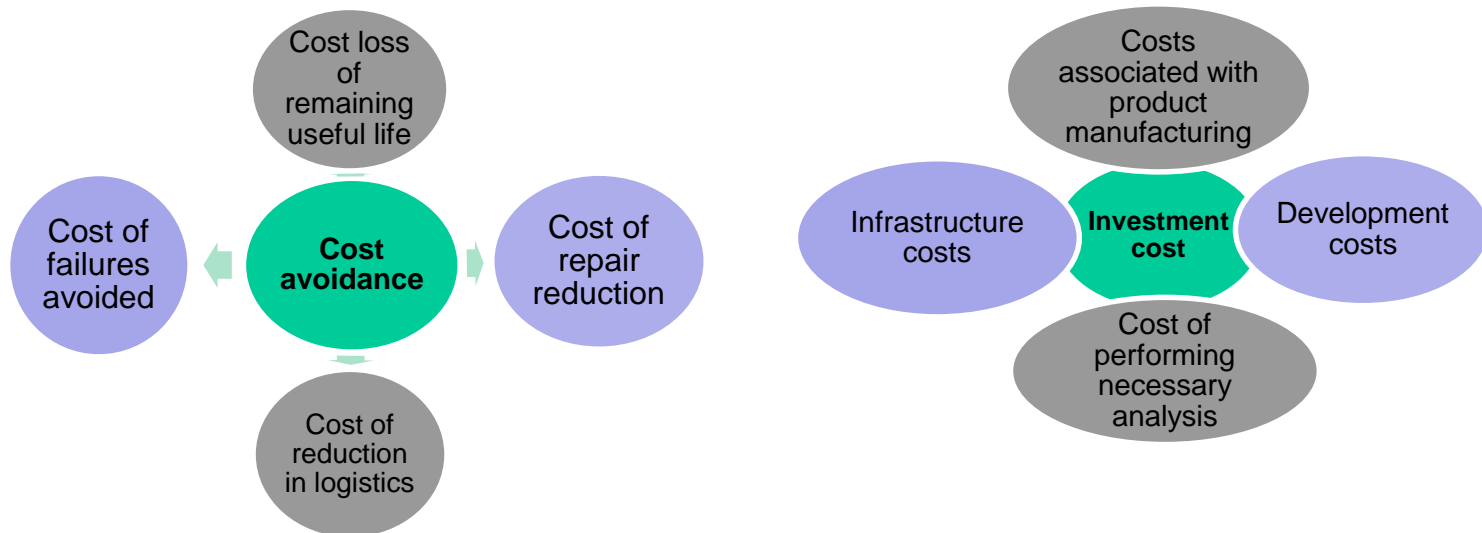
PHM &

- 1) Context Changing
- 2) Uncertainty management
- 3) Fleet
- 4) Return of Investment
- 5) Safety



- Most frequently used measure to estimate the economic benefit of PHM:

$$ROI = \frac{\text{Cost avoidance}}{\text{Investment}} - 1$$



Questions:

- 1- How to reformulate the ROI based on these economic benefits and make the ROI framework general?
- 2- How the performance indicators will affect the ROI ?



PHM &

- 1) Context Changing
- 2) Uncertainty management
- 3) Fleet
- 4) Return of Investment
- 5) Safety



Risk $\rightarrow (p_i, c_i | k)_{i=1, \dots, N}$

(Terje Aven, ESRA Webinar,
What is Risk, March 17, 2016)

PHM

- Avoided failures thanks to PHM
- Reduction of unnecessary maintenance interventions (< human errors in maintenance)
- ...
- Management of abnormal conditions
- Missing alarms of the fault detection system
- Late RUL predictions of the prognostic system
- Unexpected scenarios
- ...



PHM System

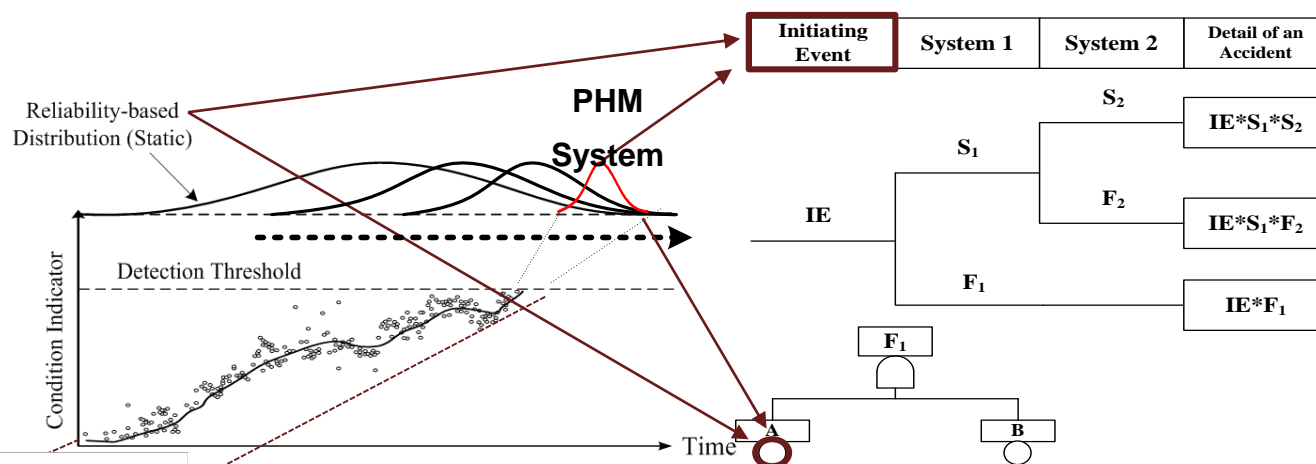
$\rightarrow (p_i^*, c_i^* | k^*)_{i=1, \dots, N^*}$



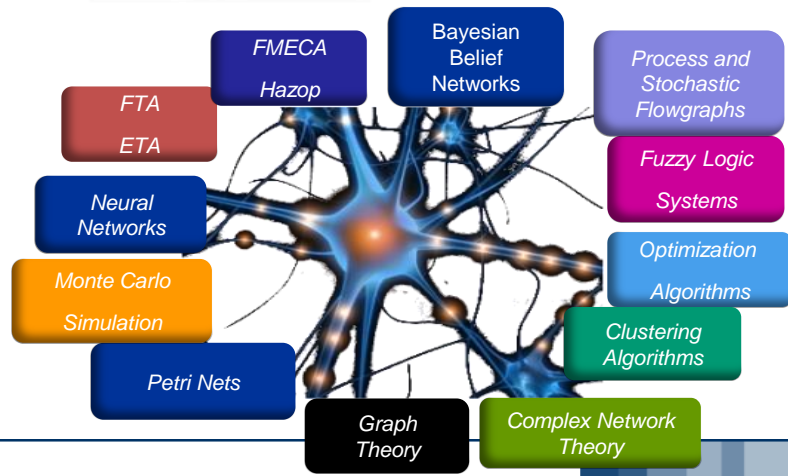
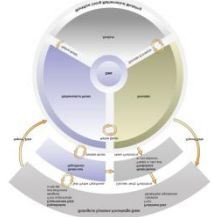
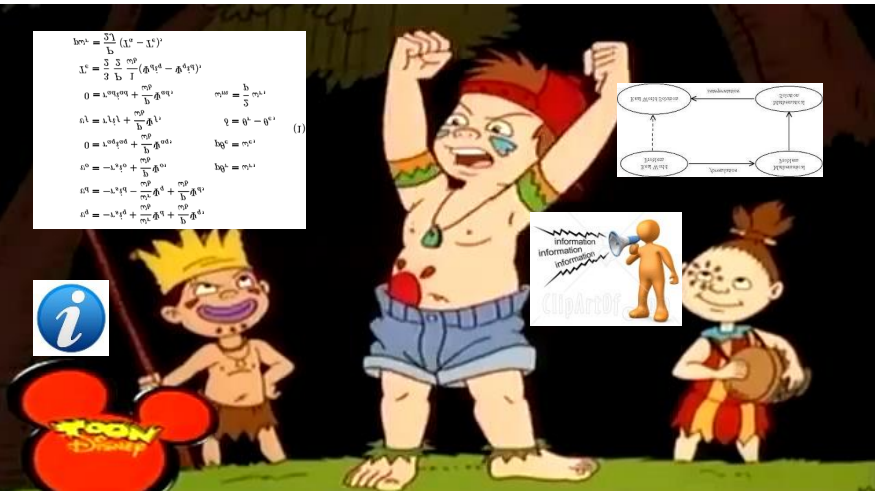
Safety?

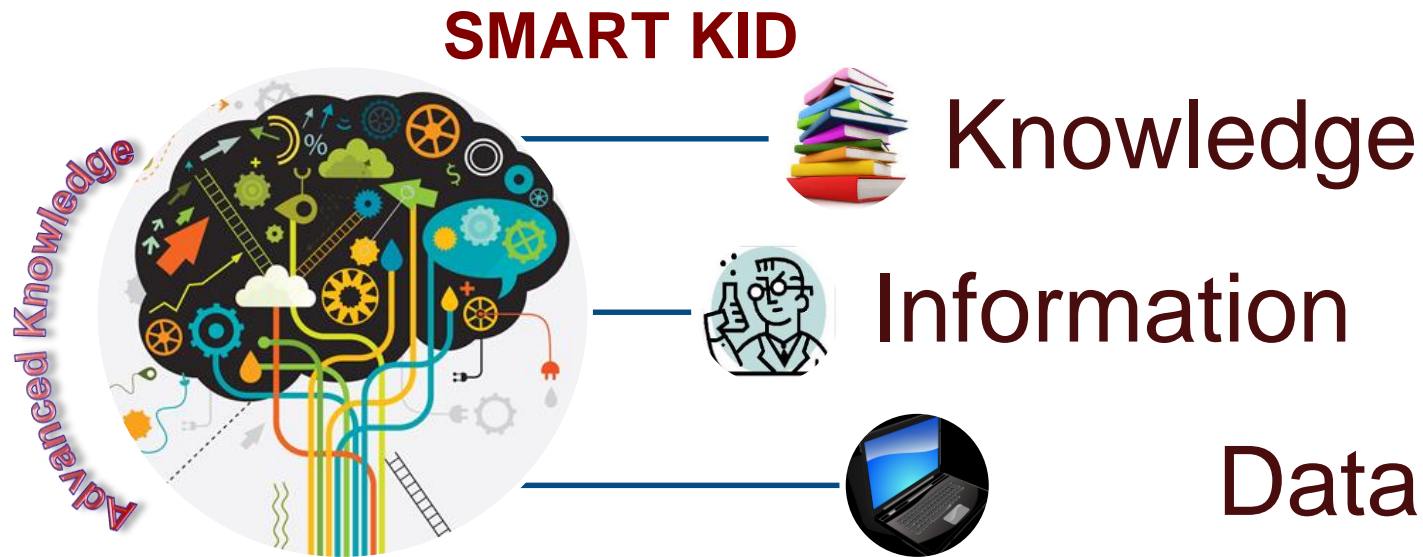


+ PHM System



Conclusions: Big KID and Smart KID





Simulation, **M**odeling, **A**nalysis, **R**esearch
for **T**reasuring **K**nowledge, **I**nformation and **D**ata
(for Reliability Engineering)



E. Zio, IEEE Trans on Reliability, 2016

Some challenges and opportunities in reliability engineering



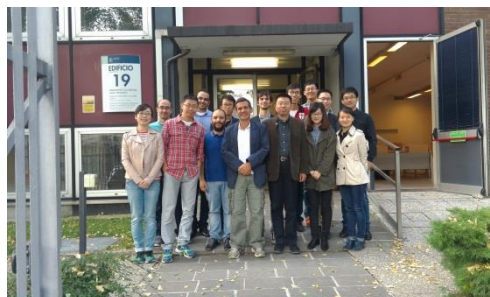


Thanks...



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...for your outstanding contributions



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